

General Formula of Linear Mixed Integral Equation with Weak Singular Kernel

Ragab O. Abd El-Rahman

Department of Mathematics, Faculty of Science, Damanhur University, Egypt

Abstract: In this paper, we consider a mixed integral equation (MIE) of the second kind. Under certain conditions, the existence of a unique solution of is discussed and proved. The kernel of position takes a singular form, while the kernel of time is continuous. Using a quadratic numerical method, the MIE leads us to a linear system of Fredholm integral equations (SFIEs). Then, SFIEs after using Toeplitz matrix method (TMM), tends to a linear algebraic system (LAS). The existence of a unique solution of LAS is proved. Finally, numerical examples are considered, and the error, in each case, is calculated.

Keywords and phrases: Mixed integral equation, Linear system of Fredholm integral equations, Linear algebraic system, Carleman function, logarithmic kernel, Toeplitz matrix method.

MSC (2010): 45B05, 45E10, 65R10.

I. Introduction

The types of integrodifferential equations (IEs) arise in a variety of applications in many fields including continuum mechanics, potential theory, geophysics, electricity and magnetism, antenna synthesis problem, mathematical physics and contact problem in the theory of elasticity, see [1-4]

In recent years, the theory of IEs has close contact with many different areas of mathematics. The following books contain many different methods to obtain the solution of the integral equation numerically, see [5-8]. The singular IEs appear in a variety of applications concerning the problems in the potential theory, see [9], wave scattering in quantum mechanics [10], diffraction problems of aero/hydroacoustics [11]. The common approach to the solution of this type involves its reduction to an equation with Cauchy and Carleman kernel.

Consider a generalized formula of linear integral equation

$$\begin{aligned} \mu \phi(x, t) = & \lambda \int_{\Omega} k(|x - y|) \phi(y, t) dy + \lambda \int_0^t \int_{\Omega} F(t, \tau) k(|x - y|) \phi(y, \tau) dy d\tau \\ & + \lambda \int_0^t G(t, \tau) \phi(x, \tau) d\tau + f(x, t), \quad (x = \bar{x}(x_1, x_2, \dots, x_n), y = \bar{y}(y_1, y_2, \dots, y_n)). \end{aligned} \quad (1.1)$$

The previous linear IEs is considered in the space $L_2(\Omega) \times C[0, T]$, $T < 1$, where Ω is the domain of integration with respect to position and $t \in [0, T]$ is the time. Here, in (1.1) the Fredholm integral term has a singular kernel $(|x - y|)$. While the Volterra integral term has the positive and continuous two kernels (t, τ) , and $G(t, \tau)$ for all time $t, \tau \in [0, T]$, $T < 1$. The coefficient λ is a constant, has many physical meanings, while, μ is a constant defining the kind of the integral equation. The given function $f(x, t)$ is called the free term, and $\phi(x, t)$ is the unknown function.

Many special cases can be derived from the integral equation (1.1),

(1) If $F(t, \tau) = 0$, we have

$$\mu \phi(x, t) = \lambda \int_{\Omega} k(|x - y|) \phi(y, t) dy + \lambda \int_0^t G(t, \tau) \phi(x, \tau) d\tau + f(x, t), \quad (1.2)$$

The above formula (1.2) is discussed in [12].

(2) If $G(t, \tau) = 0$, we obtain

$$\mu \phi(x, t) = \lambda \int_{\Omega} k(|x - y|) \phi(y, t) dy + \lambda \int_0^t \int_{\Omega} F(t, \tau) k(|x - y|) \phi(y, \tau) dy d\tau + f(x, t). \quad (1.3)$$

The solution of the above formula (1.2) is obtained in [13].

(3) If, in (1.3), $\mu = 0$, we have a MIE of the first kind, where [14] many spectral relationships are obtained in [14]

In addition the work of Abdou et al.,in[15-17] is considered special cases of this work
 In order to guarantee the existence of a unique solution of the linear equation (1.1), we assume the following conditions:

(i) The kernel of position satisfies the discontinuity condition

$$\left[\int_{\Omega} \int_{\Omega} k^2(|x - y|) dy dx \right]^{1/2} = M, \quad (M \text{ is a constant}).$$

(ii) The kernels of time $F(t, \tau)$ and $G(t, \tau)$ belong to the class $C[0, T]$, $0 \leq \tau \leq t \leq T < 1$, and satisfy for the constants, $N > N_1, N > N_2$, the conditions

$$|F(t, \tau)| \leq N_1, \quad |G(t, \tau)| \leq N_2, \quad \forall t, \tau \in [0, T].$$

(iii) The given function $f(t, \tau)$, with its partial derivatives with respect to x and t , are continuous in $L_2(\Omega) \times C[0, T]$, $T < 1$, and its norm is defined as

$$\|f(x, t)\| = \max_{0 \leq t \leq T} \left[\int_{\Omega} \int_0^t f^2(x, \tau) dx \right]^{1/2} d\tau = H, \quad (H \text{ is a constant}).$$

(iv) The unknown function $\phi(x, t)$ satisfies Lipschitz condition for the first argument and Holder condition for the second argument.

In this paper, the existence of a unique solution of the **IE** (1.1) is discussed and proved. A numerical method is used to translate the **MIE** (1.1) to a system of **FIEs** of the second kind. Then the existence of a unique solution of this system is proved. The **TMM** is used to obtain a **LAS**, where the existence of a unique solution of this system will be proved. Finally, we obtain, numerically the solution of the **LAS** when the kernel takes the weakly forms ($k(|x - y|) = \ln|x - y|, k(|x - y|) = |x - y|^{-\nu}$, $0 < \nu < 1$). Moreover, numerical results are obtained and the error estimate, in each case, is computed.

II. Quadratic Numerical Method

In this section, a quadratic numerical method is used to represent (1.1) as a **SFIEs**. For this, we divide the interval $[0, T]$, $0 \leq t \leq T < 1$

as $0 = t_0 < t_1 < t_2 < \dots < t_l < \dots < t_p = T$, where $t = t_l, l = 1, 2, \dots, p$; to get

$$\begin{aligned} \mu \phi(x, t_l) = & \lambda \int_{\Omega} k(|x - y|) \phi(y, t_l) dy + \lambda \int_0^{t_l} \int_{\Omega} F(t_l, \tau) k(|x - y|) \phi(y, \tau) dy d\tau \\ & + \lambda \int_0^{t_l} G(t_l, \tau) \phi(x, \tau) d\tau + f(x, t_l). \end{aligned} \quad (2.1)$$

Using the quadrature formula, see Atkinson [18] we have

$$\mu_l \phi_l(x) = \lambda_l \int_{\Omega} k(|x - y|) \phi_l(y) dy + H_l(x) + E_{p,l}(x), \quad E_{p,l}(x) = \max_{l_1, l_2} \{E_{p,l_1}, E_{p,l_2}\}, \quad (2.2)$$

where $\mu_l = \mu - \lambda w_{l_2} G_{l,l_2}$, $\lambda_l = \lambda (1 + u_l F_{l,l_1})$,

and

$$H_l(x) = \lambda \sum_{j=0}^{l_2-1} w_j G_{l,j} \phi_j(x) + \lambda \sum_{j=0}^{l_1-1} u_j F_{l,j} \int_{\Omega} k(|x - y|) \phi_j(y) dy + f_l(x), \quad (2.3)$$

Here, we used the following notations:

$$\begin{aligned} \phi_l(x) = \phi(x, t_l), \quad F_{l,j} = F(t_l, t_j), \quad G_{l,j} = G(t_l, t_j), \quad f_l(x) = f(x, t_l), \\ (l = 0, 1, 2, \dots, p, \quad 0 \leq j \leq l) \end{aligned} \quad (2.4)$$

The characteristic points u_j, w_j and the errors E_{p,l_1}, E_{p,l_2} , $p \approx l, l_1, l_2 < l$, are depend on the number of the derivatives of $F(t, \tau)$ and $G(t, \tau)$, respectively, to $t \in [0, T]$.

The existence of a unique solution of the (2.2), can easily be proved under the condition (i) and the following conditions

1) $\max_j \|f_j(x)\|_{L_2(\Omega)} \leq Q$, Q is a constant,

2) For the constants $L > \{Q_1, Q_2\}$, we have $\sum_{j=0}^{l-1} \max_j |u_j F_{l,j}| \leq Q_1, \sum_{j=0}^{l-1} \max_j |u_j G_{l,j}| \leq Q_2$.

III. The Toeplitz Matrix method, See Abdou Et Al. [16, 19]

Write the SFIEs (2.2), when $\Omega = [-a, a]$, as

$$\mu_l \phi_l(x) = \psi_l(x) + \lambda_l \int_{\Omega} k(|x-y|) \phi_l(y) dy. \tag{3.1}$$

Write the integral term in the form

$$\int_{-a}^a k(|x-y|) \phi_l(y) dy = \sum_{n=-N}^{N+1} \int_{nh}^{nh+h} k(|x-y|) \phi_l(y) dy, \quad (h = \frac{a}{N}). \tag{3.2}$$

Then, approximate the integral in the right hand side of (3.2) by

$$\int_{nh}^{nh+h} k(|x-y|) \phi_l(y) dy = A_n^{(l)}(x) \phi_l(nh) + B_n^{(l)}(x) \phi_l(nh+h) + E_{N,n}^{(l)}, \tag{3.3}$$

where $E_{N,n}^{(l)}$ is the estimate error. Using the principal idea of the TMM by assuming in (3.3), $\phi_l(x) = 1, x$, respectively, in this case $E_{N,n} = 0$. Hence, we have two formulas of two unknown functions $A_n^{(l)}(x)$ and $B_n^{(l)}(x)$. By solving the results, the functions $A_n^{(l)}(x)$ and $B_n^{(l)}(x)$ take the forms

$$A_n^{(l)}(x) = \frac{[(nh+h)I(x) - J(x)]}{h}, \quad B_n^{(l)}(x) = \frac{[J(x) - nh I(x)]}{h}, \tag{3.4}$$

where the values of $I(x)$ and $J(x)$ are

$$I(x) = \int_{nh}^{nh+h} k(|x-y|) dy, \quad J(x) = \int_{nh}^{nh+h} y k(|x-y|) dy, \tag{3.5}$$

Therefore, the relation (3.2), becomes

$$\int_{-a}^a k(|x-y|) \phi_l(y) dy = \sum_{n=-N}^N G_n^{(l)}(x) \phi_l(nh), \tag{3.6}$$

where

$$G_n^{(l)}(x) = \begin{cases} A_{-N}^{(l)}, & n = -N \\ A_n^{(l)}(x) + B_{n-1}^{(l)}(x), & -N < n < N \\ B_{N-1}^{(l)}(x), & n = N; 0 \leq l \leq p \end{cases} \tag{3.7}$$

The integral equation (3.1), after putting $y = mh$, becomes

$$\mu_l \phi_{l,m} - \lambda_l \sum_{n=-N}^N Y_{n,m}^{(l)} \phi_{l,n} = \psi_{l,m}, \quad l = 0, 1, 2, \dots, p, \tag{3.8}$$

The solution of the formula (3.8) takes the form

$$\phi_{l,m} = [\mu_l I - \lambda_l Y_{n,m}^{(l)}]^{-1} \psi_{l,m}, \quad |\mu_l I - \lambda_l Y_{n,m}^{(l)}| \neq 0. \tag{3.9}$$

The formula (3.8) or (3.9) represents a SAEs, where ϕ_m is a vector of $2N+1$ elements, I is the unit matrix of order $n \times m$ and $Y_{n,m}$ is a matrix whose elements are given by

$$Y_{n,m}^{(l)} = G_{n-m} + P_{n,m}, \tag{3.10}$$

$$G_{n-m} = A_n^{(l)}(mh) + B_{n-1}^{(l)}(mh), \quad -N \leq n \leq N$$

The matrix G_{n-m} is a Toeplitz matrix of order $2N+1$, where $-N \leq m, n \leq N$ and the elements of the second matrix are zeros except the elements of the first and last rows (columns). We can evaluate the values of the first row by substituting in $B_{n-1}^{(l)}(mh)$ $n = -N$ and $n = -N + i, 0 \leq i \leq 2N$, and the values of the last row (column) by substituting in $A_n^{(l)}(mh)$ $n = -N$ and $m = -N + i$.

Definition1: The TMM is said to be convergent of order r in $[-a, a]$, if for N sufficiently large, there exist a constant $D > 0$ independent of N such that

$$\|\phi(x) - \phi_N(x)\| \leq D N^{-r}, \tag{3.11}$$

The error term $E_{N,n}^{(l)}$ is determined from the following formula

$$E_{N,n}^{(l)} = \left| \int_{nh}^{nh+h} y^2 k(|x-y|) dy - A_n^{(l)}(x)(nh)^2 - B_n^{(l)}(x)(nh+h)^2 \right| = O(h_i^3), (h_i^4 \rightarrow 0). \quad (3.12)$$

The existence of a unique solution of the algebraic systemin ℓ^∞ :

For this aim, we write the system (3.8) in the operator form

$$\begin{aligned} \bar{T}\phi_{l,m} &= T\phi_{l,n} + \psi_{l,m} \quad , \quad T\phi_{l,n} = \frac{\lambda_l}{\mu_l} \sum_{n=-N}^N Y_{n,m}^{(l)} \phi_{l,n}, \quad \mu_l \neq 0 \\ \psi_{l,m} &= \frac{\lambda_l}{\mu_l} \sum_{j=0}^{l-1} u_j \left[F_{i,j} \sum_{m=-N}^N Y_{j,m}^{(l)} \phi_{j,n} + G_{i,j} \phi_{j,m} \right] + \frac{1}{\mu_l} f_{l,m} \quad , \end{aligned} \quad (3.13)$$

Then, the following lemma can be proved.

Lemma 1: If the kernel of position satisfies the conditions:

$$(i): k(|x-y|) \in L_q, (q > 1), (ii): \lim_{x \rightarrow x'} \|k(|x'-y|) - k(|x-y|)\|_{L_q} = 0, \quad x, x' \in [-a, a], \quad (3.14)$$

we have

$$\begin{aligned} a) \max_{0 \leq l \leq p} \sup_N \sum_{n=-N}^N |Y_{n,m}^{(l)}(x)| &< c, \quad c \text{ is a constant} \quad , \\ b) \lim_{m' \rightarrow m} \max_{0 \leq l \leq p} \sup_N \sum_{n=-N}^N |Y_{n,m'}^{(l)} - Y_{n,m}^{(l)}| &= 0, \quad \forall 0 \leq l \leq p. \end{aligned} \quad (3.15)$$

Proof: Firstly, we go to prove (a) of Eq. (3.15). So, from the first formula of (3.4), we obtain

$$|A_n^{(l)}(x)| = \left| (nh+h) \int_{nh}^{nh+h} |k(|x-y|)| dy - \int_{nh}^{nh+h} |y| |k(|x-y|)| dy \right| / |h|.$$

Then, using the first condition (i) of Eq. (3.14), we deduce that there exist a small constant

$$z_1, \text{ such that } \max_{0 \leq l \leq p} \sum_{n=-N}^N |A_n^{(l)}(x)| \leq z_1, \forall N. \text{ Since each term in this inequality is}$$

bounded above, hence for $x = mh$, we write

$$\max_{0 \leq l \leq p} \sup_N \sum_{n=-N}^N |A_n^{(l)}(mh)| \leq z_1. \quad (3.16)$$

Similarly, from the second formula of (3.4), we can find a small constant z_2 , such that

$$\max_{0 \leq l \leq p} \sup_N \sum_{n=-N}^N |B_n^{(l)}(mh)| \leq z_2. \quad (3.17)$$

Therefore, from the relations (3.7), (3.16) and (3.17), there exists a small constant $z \leq (z_1 + z_2)$, such that the first inequality of (3.15) is proved.

To prove (b), using the first formula of (3.4), for $x, x' \in [-a, a]$, and applying Hölder inequality, then summing from $n = -N$ to $n = N$, to have

$$\max_{0 \leq l \leq p} \sum_{n=-N}^n |A_n^{(l)}(x') - A_n^{(l)}(x)| \leq \sum_{n=-N}^n q_n \|k(|x'-y|) - k(|x-y|)\|_{L_q}.$$

Putting $x = mh, x' = m'h$, then using the condition (3.14), when $x' \rightarrow x$, we get

$$\lim_{m \rightarrow m'} \max_{0 \leq l \leq p} \sup_N \sum_{n=-N}^n |A_n^{(l)}(m'h) - A_n^{(l)}(mh)| = 0. \quad (3.18)$$

Similarly, in view of the second formula of (3.4), we have

$$\lim_{m \rightarrow m'} \max_{0 \leq l \leq p} \sup_N \sum_{n=-N}^n |B_n^{(l)}(m'h) - B_n^{(l)}(mh)| = 0. \quad (3.19)$$

Hence, from (3.18) and (3.19), the second inequality of (3.15) is proved. ■

Now, under the two conditions of lemma 3.1 and the following condition

$$(c) \max_{0 \leq l \leq \varphi} \sup_m \sum_{n=-N}^N |f_{n,m}| \leq H \quad , \quad (H \text{ is a constant})$$

We can state the following

Theorem 1: The LAS of (3.8) or (3.13), has a unique solution in the Banachspace ℓ^∞ , under the following condition

$$|\lambda_l| < |\mu_l| / (c + Lc + L) \quad , \quad (L \text{ is defined by condition 2}) \quad . \quad (3.20)$$

To prove this theorem, we consider the following two lemmas.

Lemma 2: The operator \bar{T} of Eq. (3.13) is bounded.

Proof: Let V be the set of all sequences $\Phi = \{\phi_{l,m}\}$ in ℓ^∞ such that $\|\Phi\|_{\ell^\infty} \leq \beta$, β is a constant. Define the norm of the operator $\bar{T}\Phi$ in Banach space ℓ^∞ by

$$\|\bar{T}\Phi\| = \max_{0 \leq l \leq \varphi} \sup_m |\bar{T}\phi_{l,m}|, \quad \text{for each integer } m. \quad (3.21)$$

Hence, the integral operator (3.13) takes the form

$$\max_{0 \leq l \leq \varphi} \sup_m |\bar{T}\phi_{l,m}| \leq \left| \frac{\lambda_l}{\mu_l} \right| \left\{ \max_{0 \leq l \leq \varphi} \sum_{n=-N}^N |Y_{n,m}^{(l)}| \sup_n |\phi_{l,n}| + \right. \\ \left. \max_{j=0}^l \sum_{j=0}^l \left[|u_j F_{i,j}| \sum_{n=-N}^N |Y_{n,m}^{(l)}| \sup_n |\phi_{l,n}| + |u_j G_{l,j}| \sup_m |\phi_{l,m}| \right] \right\} + \left| \frac{1}{\mu_l} \right| \max_{0 \leq l \leq \varphi} \sup_m |f_{l,m}|$$

Using condition (2), and Lemma 3.1 and condition (c), we have

$$\max_{0 \leq l \leq \varphi} \sup_m |\bar{T}\phi_{l,m}| \leq \left| \frac{\lambda_l}{\mu_l} \right| \left\{ \max_{0 \leq l \leq \varphi} \sum_{n=-N}^N |Y_{n,m}^{(l)}| \|\Phi\|_{\ell^\infty} + \right. \\ \left. \sum_{j=0}^l \left[L \max_{0 \leq l \leq \varphi} \sum_{n=-N}^N |Y_{n,m}^{(l)}| \|\Phi\|_{\ell^\infty} + L \|\Phi\|_{\ell^\infty} \right] \right\} + \left| \frac{1}{\mu_l} \right| H$$

Finally, with the aid of (3.21), we have

$$\|\bar{T}\Phi\| = \max_{0 \leq l \leq \varphi} \sup_m |\bar{T}\phi_{l,m}| \leq \alpha_2 \|\Phi\|_{\ell^\infty} + \frac{H}{|\mu_l|} \quad , \quad (\alpha_2 = |\lambda_l/\mu_l|(c + Lc + L)). \quad (3.22)$$

The inequality (3.22) shows that the operator \bar{T} maps the set V into itself, where $\beta = H/|\mu_l|(1 - \alpha_2)$.

Hence, we deduce $\alpha_2 < 1$. In addition, the inequality (3.22) involves the boundedness of the operators T and \bar{T} .

Lemma 3: The operator \bar{T} is continuous and contractive operator.

Proof: For the two sets $\Phi = \{\phi_{l,m}\}$, and $\bar{\Phi} = \{\bar{\phi}_{l,m}\}$, we have

$$\max_{0 \leq l \leq \varphi} \sup_m |\bar{T}\phi_{l,m} - \bar{T}\bar{\phi}_{l,m}| \leq \left| \frac{\lambda_l}{\mu_l} \right| \left\{ \max_{0 \leq l \leq \varphi} \sum_{n=-N}^N |Y_{n,m}^{(l)}| \sup_n |\phi_{l,n} - \bar{\phi}_{l,n}| + \max_{0 \leq l \leq \varphi} \sum_{j=0}^l \left[|u_j F_{i,j}| \right. \right. \\ \left. \left. \sum_{n=-N}^N |Y_{n,m}^{(l)}| \sup_n |\phi_{l,n} - \bar{\phi}_{l,n}| + |u_j G_{l,j}| \sup_m |\phi_{l,m} - \bar{\phi}_{l,m}| \right] \right\} \leq \left| \frac{\lambda_l}{\mu_l} \right| \left\{ \max_{0 \leq l \leq \varphi} \sum_{n=-N}^N |Y_{n,m}^{(l)}| \|\Phi - \bar{\Phi}\| + \sum_{j=0}^l \left[L \max_{0 \leq l \leq \varphi} \sum_{n=-N}^N |Y_{n,m}^{(l)}| \|\Phi - \bar{\Phi}\| + L \|\Phi - \bar{\Phi}\| \right] \right\} .$$

Hence, we get

$$\|\bar{T}\Phi - \bar{T}\bar{\Phi}\|_{\ell^\infty} \leq \alpha_2 \|\Phi - \bar{\Phi}\|_{\ell^\infty} \quad , \quad \alpha_2 < 1 \quad . \quad (3.23)$$

The previous inequality tells us that \bar{T} is a continuous operator and under condition (3.20) it is a contractive operator in ℓ^∞ . Hence, the Theorem is proved. ■

Definition 2: The estimate local error $E_{s,n}$ of (3.3) is determined as

$$\phi_l(x) - (\phi_l(x))_s = \sum_{n=-s}^s Y_{n,m}^{(l)} [\phi_l(nh) - \phi_{l,s}(nh)] + E_{s,n}^{(l)} \quad , \quad (x = mh) \quad (3.24)$$

where $(\phi_l(x))_s$ is the approximate solution of equation (3.1) .

Corollary1: Assume the hypothesis of theorem 2 are verified , then $\lim_{s \rightarrow \infty} E_{s,n}^{(l)} = 0$.

Proof: In view of formula (3.23), we have

$$|E_{s,n}^{(l)}| \leq \max_{0 \leq l \leq p} \sup_m \left| \phi_l(mh) - (\phi_l(mh))_s \right| + \|\Phi - \Phi_s\|_{\ell^\infty} \sup_n \sum_{n=-s}^s |Y_{n,m}^{(l)}| .$$

The above inequality is true for each integer , and by condition (b) , we get

$$\|E_{s,n}^{(l)}\|_{\ell^\infty} \leq (1 + c)\|\Phi - \Phi_s\|_{\ell^\infty} , \text{ for each } s . \tag{3.25}$$

Since $\|\Phi - \Phi_s\| \rightarrow 0$ as $s \rightarrow \infty$ then $E_{s,n}^{(l)} \rightarrow 0$ as $s \rightarrow \infty$. \blacksquare

Finally, it is convenient to consider the following theorem, which proves the convergence of the sequence of approximate solution $\{(\phi_l(mh))_{z,s}\}$ to the exact solution of equation (1.1) in Banachspace $L_2(\Omega) \times C[0, T]$.

Definition 3: The following relation determines the total error $E_{z,s}$:

$$E_{z,s} = \int_{-a}^a k(|x - y|) \phi(y, t) dy + \int_0^t \int_{-a}^a F(t, \tau) k(|x - y|) \phi(y, \tau) dy d\tau + \int_0^t G(t, \tau) \phi(x, \tau) d\tau - \sum_{j=0}^l u_l \left[F_{i,j} \sum_{n=-s}^s Y_{n,m}^{(l)} \phi_{j,n} + G_{j,i} \phi_{j,m} \right] - \sum_{n=-s}^s Y_{n,m}^{(l)} \phi_{j,n} \tag{4.27}$$

When $z, s \rightarrow \infty$, the sum $\sum_{l=0}^i u_l \left[F_{i,l} \sum_{n=-s}^s Y_{n,m} \phi_{l,n} + G_{i,l} \phi_{l,m} \right] + \sum_{n=-s}^s Y_{n,m} \phi_{l,n} \rightarrow$

$$\int_{-a}^a k(|x - y|) \phi(y, t) dy + \int_0^t \int_{-a}^a F(t, \tau) k(|x - y|) \phi(y, \tau) dy d\tau + \int_0^t G(t, \tau) \phi(x, \tau) d\tau ,$$

and the solution of the algebraic system becomes the solution of the equation (1.1) .

IV. Application

Consider the mixed integral equation

$$\mu \phi(x, t) = \lambda \int_{\Omega} \phi(y, t) k(|x - y|) dy + \lambda \int_0^t \int_{\Omega} t^2 \tau \phi(y, \tau) k(|x - y|) dy d\tau + \lambda \int_{\Omega} t \tau^2 \phi(x, \tau) d\tau + f(x, t) . \quad (\phi(y, t) = x^2 + t^2) \tag{4.1}$$

Example(1): Consider $k(|x - y|) = |x - y|^{-\nu}$; $0 < \nu < 1$, at $\lambda = 0.5152$; $\mu = 1$; $T = 0.2$; $n = 41$

The approximate solution and the estimate error, in each cases, for $\nu = 0.12$ and $\nu = 0.73$ are calculated in table (1).

Table1

x	Exact	v = 0.12		v = 0.73	
		App. Sol.	Error	App. Sol.	Error
-1	4.00000E-04	3.63253E-04	3.67468E-05	3.08591E-04	9.14093E-05
-0.8	2.56000E-04	2.73278E-04	1.72775E-05	2.24550E-04	3.14502E-05
-0.6	1.44000E-04	1.61339E-04	1.73390E-05	1.10959E-04	3.30406E-05
-0.4	6.40000E-05	8.14052E-05	1.74052E-05	3.00103E-05	3.39897E-05
-0.2	1.60000E-05	3.34485E-05	1.74485E-05	-1.85140E-05	3.45140E-05
0	0.00000E+00	1.74632E-05	1.74632E-05	-3.46828E-05	3.46828E-05
0.2	1.60000E-05	3.34485E-05	1.74485E-05	-1.85140E-05	3.45140E-05
0.4	6.40000E-05	8.14052E-05	1.74052E-05	3.00103E-05	3.39897E-05
0.6	1.44000E-04	1.61339E-04	1.73390E-05	1.10959E-04	3.30406E-05
.8	2.56000E-04	2.73278E-04	1.72775E-05	2.24550E-04	3.14502E-05
1	4.00000E-04	3.63253E-04	3.67468E-05	3.08591E-04	9.14093E-05

(Table (1) describes the exact and numerical solution of Eq. (4.1) when $k(|x - y|) = |x - y|^{-\nu}$; $0 < \nu < 1$, at $\lambda = 0.5152$; $\mu = 1$; $T = 0.2$; $n = 41$; for $\nu = 0.12$ and $\nu = 0.73$)

We can deduce from the above and other results the following:

- 1) When the values of λ and T are fixed, the error increases with increasing of ν , where ν is called Poisson ratio, in the theory of elasticity and when $0 < \nu < 0.5$, the atomic bond between the particles of the material is normal, while $\nu \geq 0.5$ the atomic bond is strong, for this the error may be large.
- 2) It was found that the highest error value is obtained when $\nu = 0.73$ at $x = \pm 1$. Also, the error decreases gradually, and has less value when $\nu = 0.07$.
- 3) When the values of λ and ν are fixed, the error value increases with the time.
- 4) The maximum error is 0.2363917451, at $x = \pm 1$, when $\nu = 0.73, T = 0.8$.
- 5) The minimum error is 1.81871E-7, at $x = \pm 0.0$, when $\nu = 0.07, T = 0.004$.
- 6) In all the studied situations, the error value increases when it get closer to the ends points $x = \pm 1$. It also decreases at the middle when it gets closer to zero.

Example (2): Consider the logarithmic form $k(|x - y|) = \ln|x - y|$, at $\mu = 1, \lambda = .25, n = 41, T = 0.2$.

Table 2

x	Exact	App.	Error
-1	4.00E-04	4.14364E-04	1.43636E-05
-0.8	2.56E-04	2.53924E-04	2.07618E-06
-0.6	1.44E-04	1.43201E-04	7.98768E-07
-0.4	6.40E-05	6.37610E-05	2.38987E-07
-0.2	1.60E-05	1.60212E-05	2.12470E-08
0	0.00E+00	9.86122E-08	9.86122E-08
0.2	1.60E-05	1.60212E-05	2.12433E-08
0.4	6.40E-05	6.37610E-05	2.38987E-07
0.6	1.44E-04	1.43201E-04	7.98770E-07
0.8	2.56E-04	2.53924E-04	2.07618E-06
1	4.00E-04	4.14364E-04	1.43636E-05

(Table (2) describes the exact and numerical solution of Eq. (4.1) when $k(|x - y|) = \ln|x - y|$, at $\lambda = 0.25; \mu = 1; T = 0.2; n = 41$.)

We notice from the results of the program at the previous and others cases that

- 1) When the values of T are fixed, the error values clearly increase with increasing of λ .
- 2) When the values of λ are fixed, the error values increase with the time increase.
- 3) The maximum error is 0.020521631, at $x = \pm 0.8$, when $\lambda = 0.4368, T = 0.8$.
- 4) The minimum error is 8.4973E-10, at $x = \pm 0.2$, when $\lambda = 0.25, T = 0.004$.
- 5) The error value increases when it get closer to the ends points $x = \pm 1$. It decreases at the middle when it gets closer to zero.

References

- [1]. T. Allahviranloo, Z. Gouyandeh, A. Armand, Numerical solutions for fractional differential equations by Tau-Collocation method, *Appl. Math. and Compute.* 271(2015)979-990.
- [2]. F. Ghoreishi, M. Hadizadeh, Numerical computation of the Tau approximation for the Volterra-Hammerstein integral equations, *Numer. Algor.* (2009) 52:541559.
- [3]. H.R. Marzban, H.R. Tabrizidooz, M. Razzaghi, A composite collocation method for the nonlinear mixed Volterra-Fredholm-Hammerstein integral equations, *Commun. Non. Sci. Numer. Simul.* 16 (2011) 1186-1194.
- [4]. H.L. Dastjerdia, F.M.M. Ghainia, M. Hadizadeh, A meshless approximate solution of mixed Volterra-Fredholm integral equations, *Inter. J. Comput. Math.*, 90 (2013) 527-538.
- [5]. C.D.Green, *Integral Equation Methods*, Nelson, New York, 1969
- [6]. H. Hochstadt, *Integral Equations*, A Wiley Inter Science Publication, New York, 1973.
- [7]. R. P.Kanwal, *Linear Integral Equations Theory and Technique*, Boston, 1996
- [8]. S. Schiavone, A.R.Constanta and L.Y. Mioduchowski, *Integral Methods in Science and Engineering*, Birkhauser Boston, 2002.
- [10]. Jawsan and Symm, *Integral Equation Method in Potential Theory and Elastostatics*, Academic press, London, 1977.
- [11]. David Colton and Rainer Kress, *Integral Equation Methods in Scattering Theory*, A Wiley Interscience Publication John Wiley, 1983
- [12]. W. E. Olmstead and A. K.Goutesen. *Integral representation and Oseen flow problems*, *Mech.Today*, (1976) 125 – 185 M. A. Abdou, A. A. Badr, *On a method for solving an integral equation in the displacement contact problem.* *Appl. Math. Compute.* 127 (2002) 65 – 72
- [13]. M. A. Abdou, O. L. Mustafa, *Fredholm – Volterra integral equation in contact problem*, *Appl. Math. Compute.* 138 (2003), 199 – 215
- [14]. M. A. Abdou, F. A. Salama, *Volterra – Fredholm integral equation of the first kind and spectral relationships*, *Appl. Math. Compute.* 153 (2004), 141 – 153.
- [15]. M. A. Abdou, *Fredholm – Volterra integral equation and generalized potential kernel.* *Appl. Math. Compute.* 131 (2002) 81 – 94

- [16]. M. A. Abdou, M. S. Ismail, *Toeplitz matrix and product Nystrom methods for solving the singular integral equation*, *Le Matematica* Vol. LVII (2002) – FascLPP. 21 – 37
- [17]. M. A. Abdou, Mohamed and Ismail, *On the numerical solutions of integral equation of mixed type*, *Appl. Math. Compute.* 138, (2003) 172 – 186
- [18]. K.E. Atkinson, *The Numerical Solution of Integral Equation of the Second Kind*, Cambridge University, Cambridge, 1997
- [19]. M. A. Abdou, M. M. EL-Borai, M. M. El-Kojok, *Toeplitz matrix method and nonlinear integral equation of Hammerstein type*, *J. Comp. Appl. Math.* Vol. 223, (2009) 765 – 776